SUITABILITY OF TAPERED FLANGE I-SECTIONS IN SEISMIC MOMENT RESISTING FRAMES

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ABSTRACT: Tapered flange sections offer difficulties of providing connections that are expected to resist overstrength plastic moments of members and associated shear. However, some earthquake prone countries still are using tapered flange sections for constructing buildings to resist severe seismic shaking. Tapered flange sections available in India not only offer low sections properties (moment of inertia *I*, flange width *b*), but also do not meet the internationally accepted stability requirements. This paper highlights deficiencies in tapered flange sections and reiterates some important issues in earthquake-resistant connection design.

Keywords: Tapered flange sections; seismic design; moment frames; stability; compact section; connection design; plastic; overstrength

1. INTRODUCTION

Satisfactory performance of steel structures in high seismic regions primarily depends on three factors in design namely strength, stability and ductility of individual members. Apart from these, connections play an important role in the overall performance of the structure; inadequate connections can result in failure of the structure even if the structural members are adequately designed. Designed connections, together with a predetermined collapse mechanism under strong seismic shaking can result in good overall performance of the structure. In many Asian countries, including India, hot-rolled tapered flange sections are still commonly used in construction of multi-storey steel frame buildings. This paper reviews international state-of-the-art seismic design specifications for steel I-sections and evaluates the suitability of tapered-flange sections use in high seismic areas.

2. EARTHQUAKE HAZARD AND STEEL CONSTRUCTION – THE INDIAN SCENARIO

Over the past two decades, India has experienced a spate of earthquakes that caused large damage to residential and industrial structures (i.e., 1984 M5.6 Cachar earthquake, 1988 M6.6 Bihar earthquake, 1991 M6.6 Uttarkashi earthquake, 1993 M6.4 Killari earthquake, 1997 M6.0 Jabalpur earthquake, 1999 M6.5 Chamoli earthquake, 2001 M7.7 Bhuj earthquake, 2002 M6.5 Diglipur earthquake, 2004 M9.3 Sumatra earthquake, and 2005 M7.7 Kashmir earthquake). Besides, during the five decades from 1897 – 1950, India had experienced four great earthquakes (M>8), i.e., 1897 M8.7 Assam earthquake, 1905 M8.6 Kangra earthquake, 1934 M8.4 Bihar-Nepal earthquake and the 1950 M8.6 Assam-Tibet earthquake. Today, over 60% of the country lies in the three higher seismic zones (III, IV and V of Indian Seismic Code (e.g. IS 1893 Part 1 [1]) and only about 3 % of the built environment (of over 250 million houses) is engineered. Even these engineered structures are under suspect owing to poor seismic design practice. Thus, India has potential for strong seismic shaking, and the large stocks of existing buildings are vulnerable. The situation is similar in

many neighbouring countries. In general, reinforced concrete and masonry are still the common choice over steel as a building material. However, recent trends in some of these countries show substantial growth in steel consumption. This is largely attributed to increase in low-to-medium rise residential and office buildings in urban centers. For this, available hot-rolled standard tapered-flange sections are being used.

3. SECTION GEOMETRY

An important feature of tapered flange sections is the slope in the flange thickness. Due to this slope or taper, bolt-shank bends on tightening thereby increasing the chances of its failure. Also, because of the tapered and thin tip of the flange, only small size welds are possible between the cover plate and the flange tip (Figure 1). Moreover, proper welding between surfaces at such obtuse angle is difficult; also, it increases chance of brittle failure of the weld. Another concern is the small flange width of the sections; the largest is only 250 mm wide. Small flange width allows use of only one bolt on either side of the web and therefore requires unduly large connection length. Poor and unreliable welding in welded connection scheme and large connection length in bolted connection scheme puts the cover-plated connections of tapered flange sections in jeopardy; only hot-rolled sections with uniform thickness flanges should be used in seismic applications as in countries with advanced provisions in seismic design of steel structures, like the USA [2, 3].

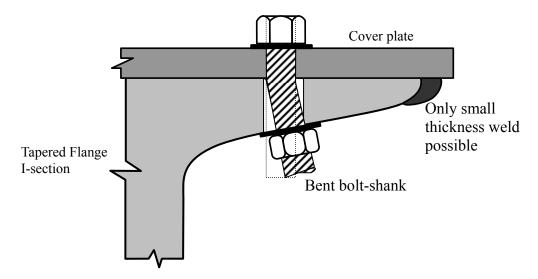


Figure 1. Effects of Tapered Flange: (i) Bolted Connection: Bolt Shank gets Bent on Tightening from the Original Straight Alignment and (ii) Welded Connection: Only Obtuse Angled Small Thickness Weld Possible at the Tapered Tip

4. STABILITY

Steel as a material has intrinsic ductility. But, the ductility in steel structures is primarily achieved through a design and construction process that ensures stable post-yield behaviour of the material. This entails stringent stability provisions that ensure formation of plastic hinges.

Considering the major instabilities in steel structures (e.g., lateral torsional buckling of beams, flexural buckling of columns, and local buckling of beam-column flanges and webs), and the expected level of inelastic deformation and ultimate strength achieved, sections are grouped as compact, semi-compact and slender sections. Design codes use slenderness or b/t ratios to identify stability limits of flange and web plates to demarcate these groups of sections. The AISC Specifications (e.g. Specifications for Structural Steel Buildings [2]) and Provisions (e.g. Seismic Provisions for Structural Steel Buildings [3]) have these limits as: (a) λ_{ps} : slenderness limit for compact elements with a minimum guaranteed ultimate strength M_p (nominal plastic moment capacity) and plastic rotation ductility, (b) λ_p : slenderness limit for compact elements with only minimum guaranteed strength M_p , and (c) λ_r : slenderness limit for non-compact elements with only minimum guaranteed strength M_{ν} (Figure 2). Sections with slenderness ratio λ of flanges and web elements $> \lambda_r$, classified as slender sections buckle locally even before reaching their yield moment capacity M_y . Sections with $\lambda_p < \lambda < \lambda_r$, classified as non-compact sections just reach the yield moment. Sections with $\lambda_{ps} < \lambda < \lambda_p$, classified as compact sections, develop the member plastic capacity M_p with limited ductility, while sections with λ less than λ_{ps} develop full member plastic capacity M_p and sufficient plastic rotation.

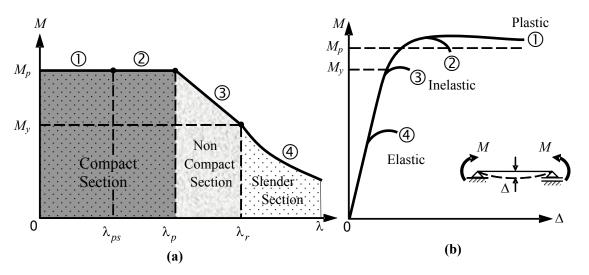


Figure 2. Effect of Slenderness on Developable Member Capacity:

(a) Strength-Slenderness Ratio Relationship; (b) Moment-Deflection Behavior of I-Sections, for Different Levels of Slenderness. Inelastic Buckling Commences much before Yield Moment M_y is Reached because of Residual Stresses

For steel with nominal yield strength $F_y = 250$ MPa, the above slenderness limits are presented. Plastic design in the Indian Standard (IS-PD) (e.g. IS 800 [4]) limits the maximum unsupported flange width-to-thickness ratio to 8.6, and the maximum web depth-to-thickness ratio to 43.5 for P/P_y exceeding 0.27, 70.8 for zero axial force, and linearly varying for intermediate axial force values. In comparison, the AISC Load and Resistance Factor Design specifications (AISC-LRFD) (e.g. Specifications for Structural Steel Buildings [2]) limits maximum unsupported flange width-to-thickness ratio to 10.7 for compact sections and to 28.2 for non-compact sections. And, the web depth-to-thickness ratio is limited to 106.2 for compact sections and 161.2 for non-compact sections. The AISC Provisions (e.g. Seismic Provisions for Structural Steel Buildings [3]) limits are even more stringent: 8.5 for beam flange and 69.2 for beam web of seismically compact sections, and 42.1 for column webs.

The Indian Standard Handbook (e.g. SP: 6(1) [5]) classifies Indian Standard hot-rolled I-section beams into four categories namely, light (ISLB), medium (ISMB), wide flange (ISWB) and heavy (ISHB). These sections (originally used in British practice) have unique feature of tapered flanges with rounded corners at the flange tips. For the purpose of design, a nominal thickness is used for these tapered flanges. The comparison of width-to-thickness ratios of flange and web plates of the available and commonly used hot-rolled tapered flange I-shaped sections used in India are shown in Figures 3 and 4. The cross-sectional dimensions can be found elsewhere (e.g. SP: 6(1) [5]). The flange and web width-to-thickness ratios of sections with maximum depth of 600 mm or flange width of 250 mm, do not comply with the seismically compact section limits. Hence, structures made with these sections are seismically deficient.

Apart from section compactness, member stability is another important requirement for good seismic performance of the structure. IS-PD limits maximum slenderness ratio to 120 for columns. AISC Specifications limits maximum slenderness ratio to 133 for columns when inelastic analysis and design are performed. For the usual storey height, tapered flange sections fail to comply with required member slenderness for columns under strong seismic action because of their small radius of gyration; additional flange plates are required if these sections are to be used in moment resisting frames (MRFs) intended to resist seismic actions (e.g. Paul, Murty and Jain [6]). As a result, it is expected that these frames built with these sections would exhibit a poor post-yield behaviour, under strong seismic shaking.

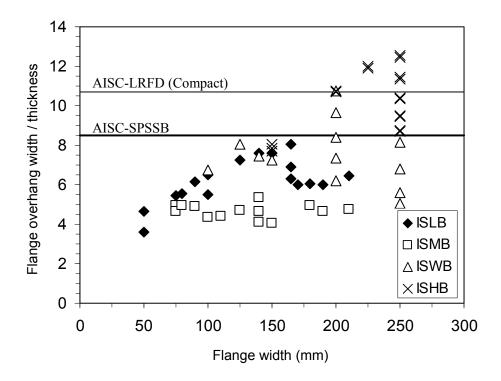


Figure 3. Flange Width-to-Thickness Ratio of Indian Hot-Rolled Tapered Flange I-Sections: Some Sections do not Comply with the Seismically Compact Section Limit Even when the Maximum Available Flange Width is only 250 mm

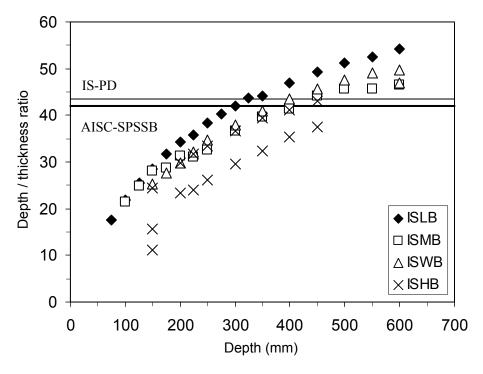


Figure 4. Web Depth-to-Thickness Ratio of Indian Hot-Rolled Tapered Flange I-Sections: Sections with Higher Depth do not Comply with the Seismically Compact Section Limit even when the Maximum Available Depth is only 600 mm

5. STIFFNESS AND STRENGTH

A comparison is made of stiffness and strength of the tapered flange sections with representative parallel wide flange AISC sections commonly used in seismic design (Tables 1 and 2). The maximum depth of Indian tapered flange sections is 600 mm, and the largest moment of inertia I_{xx} (about strong axis of bending) and nominal plastic moment capacity M_p are 1156×10^{-6} m⁴ and 987 kNm respectively. However, I_{xx} and M_p of AISC sections of same depth are at least about 3 times higher than those of the tapered flange sections of same depth (Figures 5 and 6). Thus, structures built with even the largest tapered flange sections are too flexible and too weak relative to their international counterparts with parallel flange sections.

6. CONNECTION DESIGN

Following the large number of connection failures during the 1994 Northridge (USA) and 1995 Kobe (Japan) earthquakes, a fresh approach emerged for the design of beam-to-column and column-to-base connections. Beam-to-column connections are designed now as per the *Capacity Design Concept*. By this design method, premature fracture of welds or fasteners is avoided at the connection; beams and columns undergo ductile yielding and connections remain elastic when designed for the maximum demand arising from the beam or column under plastic condition (Figures 7 and 8). In summary, the capacity design concept enlists a strength hierarchy of the components of a building: (a) the beam-to-column connections joint are to be stronger than the beam, (b) the columns are to be stronger than the beams, and (c) the column base connections are to be stronger than the column (e.g. Penelis and Kappos, 1997 [7]).

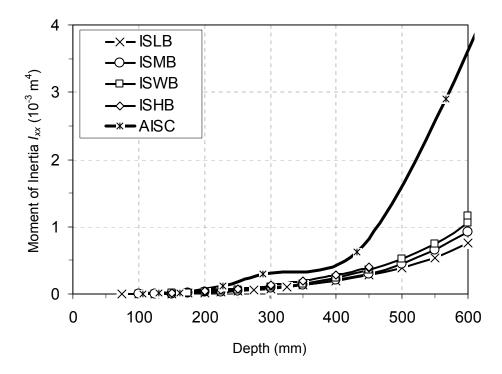


Figure 5. Comparison of Moment of Inertia of Representative AISC and IS Hot-Rolled Tapered Flange I-Sections: Tapered Flange Sections are much smaller than the AISC Parallel Wide Flange Sections

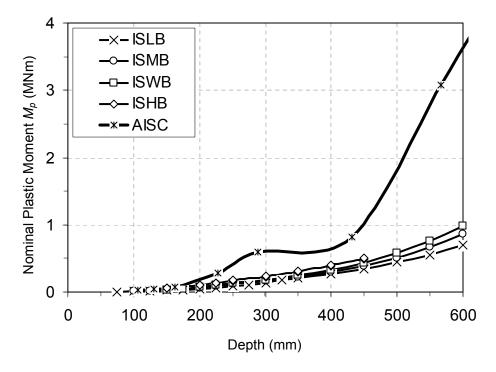


Figure 6. Comparison of Nominal Plastic Moment of Representative AISC and IS Hot-Rolled Tapered Flange I-Sections: Tapered Flange Sections are much smaller than the AISC Parallel Wide Flange Sections

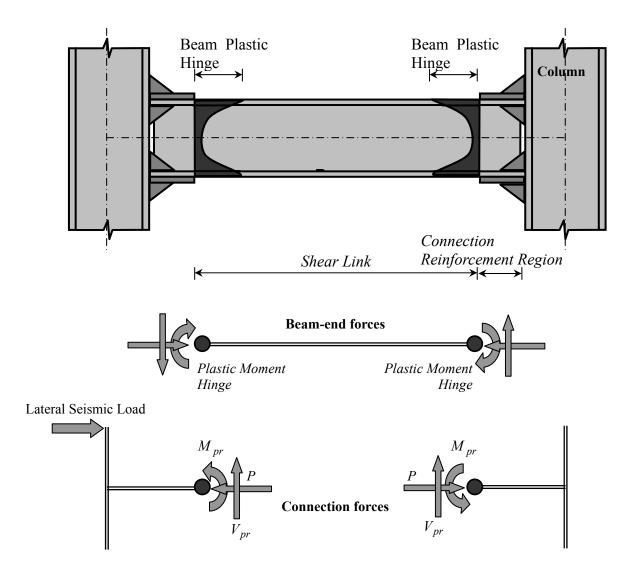


Figure 7. Location of Ductile Plastic Hinges Adjacent to Beam-to-Column Connections: Connection Reinforcement Elements help in Pushing the Inelasticity Away from the Column Face

The connection design forces should be designed for the maximum probable member strength, i.e., moment capacity M_{pr} and the associated equilibrium compatible shear V_{pr} , including effect of gravity load. In using M_{pr} in connection design, three important issues need attention. Following the Northridge and Kobe earthquakes, coupon tests of specimens taken from actual construction and mills have shown that the actual yield strength of steel in rolled-sections can be higher than the minimum specified yield strength F_y (e.g. Engelhardt and Sabol [8]; Malley and Frank [9]). As a result, AISC Provisions recommends the use of higher yield strength for calculating member strength for the determination of connection element design force; the ratio R_y of the expected yield strength to the minimum specified yield strength of the member is to be used. For instance, for ASTM A36 grade steel, R_y is 1.5; at least a 50% increase in connection design force is recommended. However, In India, such data for the available tapered flange sections are not readily available in public literature, and also, the current code provisions do not account for this. Such statistical data from the hot-rolled tapered flange sections obtained through coupon test need to be incorporated in seismic design procedures.

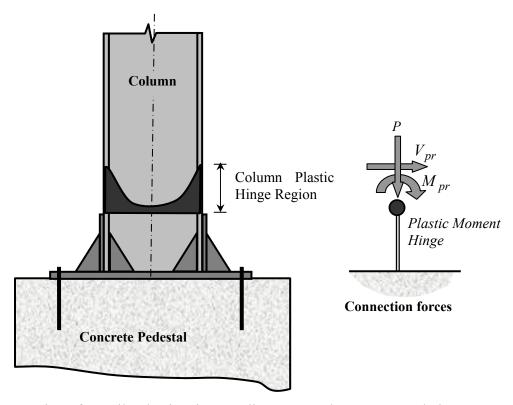


Figure 8. Location of Ductile Plastic Hinges Adjacent to Column-to-Foundation Connections: Connection Reinforcement Elements help in Pushing the Inelasticity away from the Base Plate

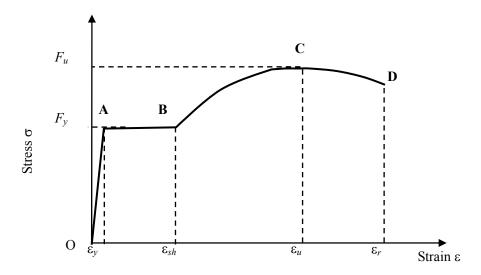


Figure 9. Typical Schematic of Constitutive Curve of Structural Steel: Four Distinct Zones are Evident - A Linear Elastic Zone OA, a Yield Plateau AB, a Strain-Hardening Zone BC and a Strain-Softening Zone CD

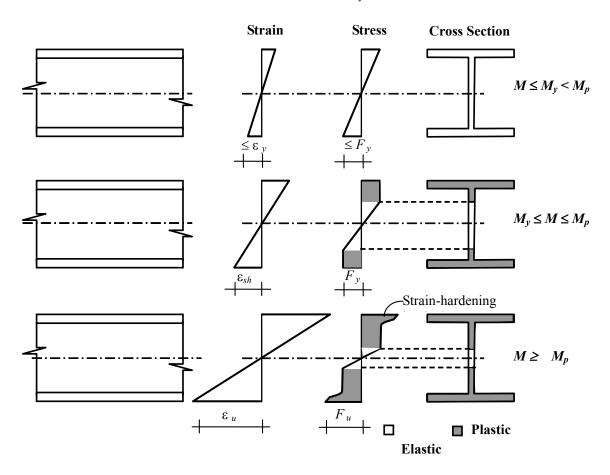


Figure 10. Various Stages of Member Plastification under Pure Flexure: The Fibers at Neutral Axis do not Yield, but the Fibers away from the Neutral Axis Strain-Harden, thus the Cross-Section Develops a Nominal Plastic Moment of M_p and more

Design codes often (e.g., AISC [2], IS:800 [4]) assume an idealized elastic perfectly plastic constitutive law for structural steel with characteristic yield strength as F_{ν} . In reality, structural steel has a distinct constitutive relation (Figure 9) with an initial elastic zone (OA), a yield plateau (AB), a strain hardening zone (BC), and a strain-softening zone (CD) before it fractures. The member nominal flexural capacity M_p for bending about the major axis is computed based on the idealized rectangular stress block with a maximum stress of F_y . Such a stress block is not practically achievable, because to develop a stress of F_{ν} at the fibers at and near the neutral axis, the strains required at the extreme fibers of the section are infinitely large. Secondly, the rectangular stress block can never be achieved without inevitable strain-hardening of the extreme fibers of the beam section. Thus, the representation using rectangular stress blocks deviates from the actual behavior (Figure 10). The beam bending moment equal to the plastic moment value M_p can be realized in a section only when a part of it undergoes strain-hardening while some of it still remains elastic; experimental studies (e.g. Popov et al. [10], Chen and Lui [11], Englehardt and Sabol [8]) showed that beam capacities larger than M_p are achievable with inelastic deformations corresponding to the drift demands expected by some code guidelines (e.g. UBC [12]; FEMA, [13]). Thus, it is the strain hardening of steel that causes an increase in the member capacity, and hence the demand on connections, under strong seismic shaking over the code-prescribed nominal capacity M_p . AISC and FEMA (e.g. AISC [14]; FEMA [15]) recommends strain-hardening factors greater than unity to account for beam overstrength, and increase in connection design strength over M_p ; 10-20% increase is recommended. A simple expression, involving the minimum specified yield and ultimate strengths (e.g. FEMA [16]) is given as

$$C_{pr} = \frac{F_y + F_u}{2F_y} = 1 + \frac{1}{2} \left(\frac{F_u - F_y}{F_y} \right),\tag{1}$$

where F_y and F_u are the specified minimum yield and tensile strengths of the (beam) material, respectively. Later, a more rational approach to estimate R_s was presented (e.g. Arlekar and Murty [17]). For any section, normalized moment M/M_p versus normalized curvature relations can be generated. φ is the curvature of the section, and φ_y , referred to as yield curvature when the farthest material point from the neutral axis reaches yield. Then, the normalized moment M/M_p is the strain hardening factor R_s , and is a measure of strain hardening in the beam. And, φ/φ_y is the curvature ductility μ_{φ} . Based on a study of 61 hot-rolled tapered-flange I-sections (Table 1), the expression for strain hardening factor R_s was given as (e.g. Goswami, Arlekar and Murty[18]) (Figure 11)

$$\frac{M}{M_{p}} = R_{s} = \begin{cases}
\mu_{\phi} & \text{for } 0 \leq \mu_{\phi} \leq \mu_{y} \\
1 & \text{for } \mu_{y} < \mu_{\phi} \leq \mu_{sh}, \\
0.81 + 2\left(\frac{\mu_{\phi}}{100}\right) - 2\left(\frac{\mu_{\phi}}{100}\right)^{2} + \left(\frac{\mu_{\phi}}{100}\right)^{3} - 0.3\left(\frac{\mu_{\phi}}{100}\right)^{4} & \text{for } \mu_{sh} < \mu_{\phi} \leq \mu_{u}
\end{cases} \tag{2}$$

where μ_y is the curvature ductility at idealized yield, μ_{sh} is the curvature ductility at the beginning of strain-hardening on the idealized curve, and μ_u is the ultimate curvature ductility. From the data of the 61 sections considered, the values of μ_y , μ_{sh} and μ_u are obtained as 1.0, 11.4 and 150 respectively. Further, curvature ductility μ_{ϕ} imposed at a section can be estimated from the amount of plastic rotation θ_p required to be developed at the end of the member, using

$$\mu_{\varphi} = \frac{2EI\theta_{p}}{M_{p}d} \,, \tag{3}$$

where d and EI are the depth and flexural rigidity of the member. Early experiments have shown that plastic rotation demand of 0.03-0.04 can be achieved without significant loss in strength (e.g., FEMA [13]). Since Indian steel code specifies no such demand, experiments need to be conducted on MRFs made using the available tapered-flange sections to determine desirable plastic rotations and develop associated design guidelines. Still, using Eq. 3, the curvature ductility μ_{ϕ} of the sections considered ranges from 7.0 to 29.0 for θ_p varying between 0.01 and 0.04 radians. Then, using Eq. 2, the value of R_s , hereinafter called the strain-hardening factor, is estimated to be in the range 1.0 to 1.24 for the available tapered-flange I-sections. The above expression for R_s was derived for ASTM A36 grade steel with F_v equal to 250 MPa, and F_u/F_v as 1.5.

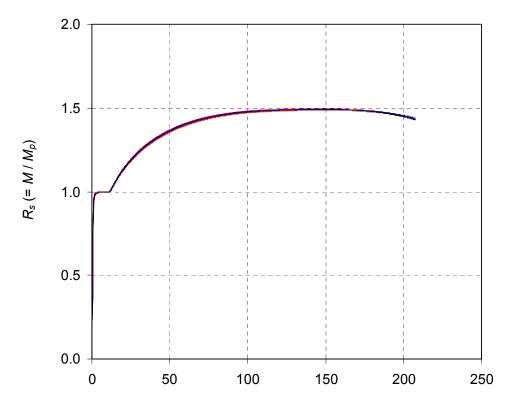


Figure 11. Strain-Hardening of Tapered-Flange I-Sections: Strain-Hardening Factor from Study using 61 Hot-Rolled Tapered-Flange I-Sections with $F_u/F_v = 1.5$

Though member capacity that can be mobilized (and thus, connection design force) is increased due to strain-hardening and uncertainty in material yield strength, section and member instabilities cause reduction of member capacity and connection design force. A compactness factor R_c , is introduced to account for the reduction in the maximum achievable member capacity owing to premature local buckling given by

$$R_{c} = \begin{cases} 1.0 & \text{for } \frac{b}{t} \leq \lambda_{p} \\ 1.0 - 0.2 \left\{ \frac{(b/t) - \lambda_{p}}{\lambda_{r} - \lambda_{p}} \right\} & \text{for } \lambda_{p} < \frac{b}{t} \leq \lambda_{r} \\ 0.8 & \text{for } \frac{b}{t} > \lambda_{r} \end{cases}$$

$$(4)$$

Here, the minimum value of R_c is 0.8. The limiting values for λ_r and λ_p are prescribed in the codes. However, the limits prescribed in the codes are originally for the purpose of beam flexural design and thus, will tend to give a conservative underestimate of the member strength. But, in connection design, the upper bound strength is required. Moreover, these values are for prismatic flange and web. For hot-rolled I-sections with tapered flanges, such limits of λ_r and λ_p for connection design purpose and dependence of R_c on these need to be prescribed.

Using R_y , R_s , and R_c , the maximum probable member strength, and hence, the maximum probable demand on the connection elements in beam-to-column connections is given by

$$M_{pr} = R_{\nu} R_s R_c M_p . ag{5}$$

Column-to-foundation connection (Figure 8) design on the other hand also requires proper account of the axial load on the column, which is often varying, particularly under strong seismic shaking. Further, interactions between axial force, shear force and bending moment capacities of the section need to be looked into in arriving at the connection design forces. In addition, design codes consider the minimum specified yield strength F_y as the limiting strength for capacities and the interactions. This is acceptable for design of the members. However, it is required to properly estimate the maximum possible capacities along with the interactions considering strain-hardening for design of connection elements. Thus, section capacities of tapered-flange I-sections are developed using a fiber model and hysteretic loading and unloading of steel constitutive law (Figure 12). Figure 13 shows typical P-V-M interaction surface of a tapered-flange I-section (e.g., ISMB 600, with section properties as given in Table 1). While developing the P-V-M interaction curves, the following is considered. For a given normal stress σ_{xx} (due to axial load and bending moment) in a fiber, the von Mises yield criterion for steel represented by

$$\sigma_{xx}^2 + 3\tau_{xz}^2 = Y^2 \,. \tag{6}$$

is used to calculate the available shear capacity. Here, Y is taken as the ultimate stress F_u . The curvature is increased from zero to a maximum value corresponding to the maximum rupture strain ε_r at the extreme fiber, and at each level, the shear and normal capacities are estimated. The uniaxial stress-strain curve of steel (Figure 11) has a drop in the stress beyond the strain corresponding to the ultimate stress. The limiting shear stress from Eq. 6 when $\sigma_{xx} = F_u$, is zero. For strains greater than ε_u , Eq. 6 suggests that the shear stress τ_{xz} in fibers is non-zero. However, in this study it is assumed that all fibers having strains beyond ε_u do not have shear capacity. Further, while obtaining the limiting V-M boundary, it is assumed that beam flanges and webs do not undergo buckling. The nominal shear strength $\left(V_p = \tau_y t_w d\right)$ and the nominal bending moment capacity $\left(M_p = F_y Z\right)$ of the section are used to normalize the shear and moment capacities, respectively. The first yield shear stress corresponding to a state of pure shear is used and defined as $\tau_v = F_v / \sqrt{3}$.

The most commonly used section capacity interaction in design is the P-M interaction. Figure 14 shows P-M interactions developed for the tapered-flange section considering strain-hardening using the fiber model. Design codes often assume a linear interaction (for ease in design) and uses yield strength as the limiting strength. Figure 14 also shows the linear interaction recommended by the Indian code (IS 800 [4]) along with the scaled interaction up to the ultimate capacity. The code specified curve depicts an average member capacity for moments up to about M_p . Thus, it underestimates the moment capacity of some members, and hence, connections designed using this interaction would be under-designed. Hence, an upper bound of the P-M interaction curves at zero shear is derived as

$$\frac{M}{M_p} = \frac{F_u}{F_y} \left(1 - \frac{F_y}{F_u} \frac{P}{P_y} \right)^{1.54} . \tag{7}$$

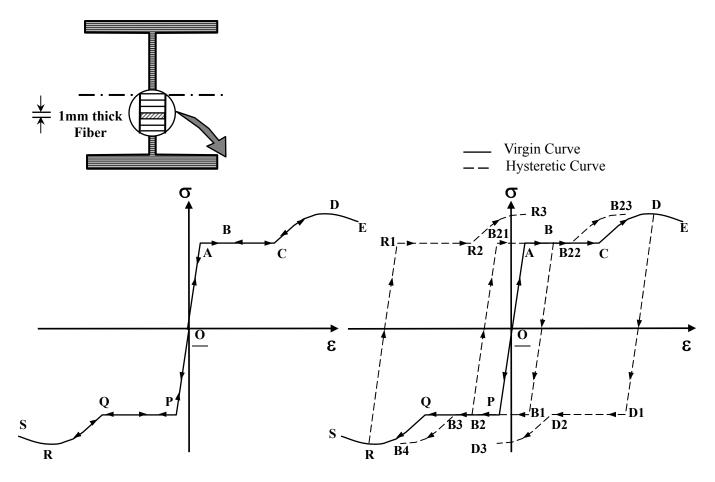


Figure 12. Fiber Model Showing the Discretization of the Beam Section along with the Explicit form of Stress-Strain Relationship for Steel Along with Schematic Representation of the Loading and Unloading Paths for Steel

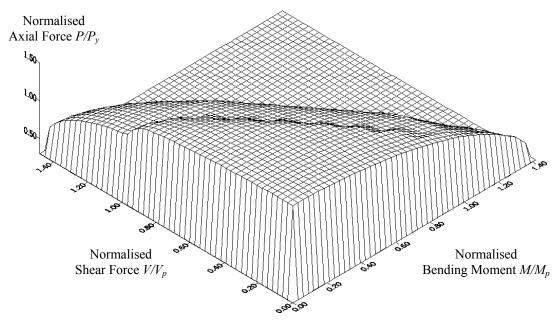


Figure 13. Strength Interaction in ISMB 600: Normalized *P-V-M* Interaction Surface of ISMB 600 Generated using Hysteretic Stress-Strain Model

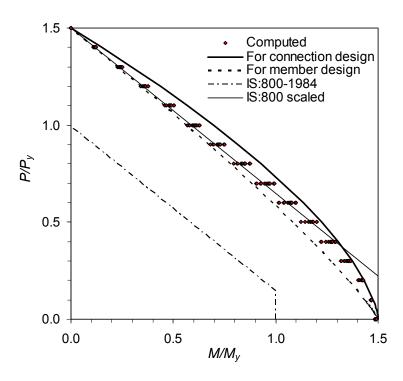


Figure 14. P-M Interaction Curve along with the Actual P-M Points for V = 0 for Indian Hot Rolled I-Sections

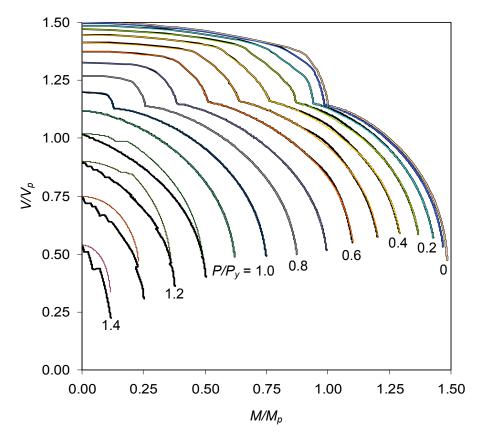


Figure 15. Shear-Moment Interaction showing Normalized *V-M* Curves for a Typical Tapered-Flange I-Section (ISMB 600) for Different Axial Load Levels with and Without Hysteretic Stress-Strain Ccurve.

This upper bound limit is conservative for ascertaining the connection demand forces, although, using this for member design would result in an overestimate of the member capacity. Figure 15 shows normalized V-M interaction curves for a typical tapered-flange I-section (ISMB 600) for various levels of the compressive axial loads. The moment is normalized with the nominal plastic moment capacity M_p and shear with the nominal shear capacity V_p . The V-M interaction curves obtained using strain-hardened virgin stress-strain curve are also shown in Figure 15. The V-M curves without hysteretic loading (represented by thinner lines) are higher than the corresponding curves obtained using the hysteretic loading (represented by thicker lines), only when the axial load is higher than the yield load P_y . Thus, the V-M curves with non-hysteretic loading, commonly used in codes, are acceptable in static design where the axial load does not change or is below the member yield load. However, under earthquake shaking, the axial load can swing by large amount and the V-M curves with hysteretic loading better reflect the actual lower member capacity and should be considered for the member design.

Unlike for beam-to-column connection design, the connection design forces for column-to-foundation design forces needs to account also for the various strength interactions stated above. However, as in beam-to-column connection design, additional strength reductions result due to member instabilities like global flexural buckling in compression and global flexural—torsional buckling. For instance, the reduction due to flexural buckling in compression can be taken into account through a modification factor R_{λ} as

$$R_{\lambda} = \begin{cases} 0.658^{\lambda_c^2} & \text{for } \lambda_c \le 1.5\\ \\ \frac{0.877}{\lambda_c^2} & \text{for } \lambda_c > 1.5 \end{cases}$$

$$(8)$$

where λ_c is the global slenderness parameter given by

$$\lambda_c = \frac{KL}{r\pi} \sqrt{\frac{F_y}{E_s}} \,, \tag{9}$$

in which, K is the effective column length factor, L the length of the column, and r the governing radius of gyration, and F_y and E_s the yield strength and modulus of elasticity of steel, respectively. Similarly, the reduction due to flexural–torsional buckling can be accounted through a factor R_L given by

$$R_{L} = \left[\frac{\pi^{2} E_{s} C_{w}}{(K_{z} L)^{2}} + G_{s} J \right] \frac{1}{(I_{x} + I_{y}) F_{y}},$$
(10)

where C_w is the warping constant, K_z the effective length factor for torsional buckling, G_s the shear modulus of steel, J the torsional constant, and I_x and I_y the moment of inertia about the x and y axes, respectively. Thus, the maximum probable column moment capacity M_{pr}^P under axial load P that can be mobilized (or the design moment for column-to-foundation connection design) is given by

$$M_{pr}^{P} = R_{\nu} \operatorname{Min}[R_{c}; R_{\lambda}; R_{L}] M_{p}^{P}. \tag{11}$$

Unlike in Eq. 5, the strain-hardening factor is not explicitly used (in Eq. 11) because with the varying column axial force levels during seismic shaking, the level of strain-hardening also varies. Instead, the capacity curves are developed considering possible strain-hardening.

Using the design forces given by Eqs. 5 or 11, the connections need to be designed. However, in executing the design, various concerns arise in use of tapered-flange sections; it is particularly serious for bolted connections. Typically, the beam flanges are expected to transfer the bending moment, and the beam web the shear forces. However, recent studies have shown that this assumption is not realistic, and a truss analogy model is necessary to represent the realistic flow of forces in the connection (e.g. Lee, Goel and Stojadinovic [19]; Arlekar and Murty [20]). An improved welded cover plated and ribbed moment connection is necessary to transfer the overstrength based design forces (e.g. Arlekar and Murty [20]). Here, the cover plate is designed to transfer part of the bending moment in the form of axial (compressive or tensile) forces, while two outer rib plates are designed to transfer both axial and shear forces (Figure 16).

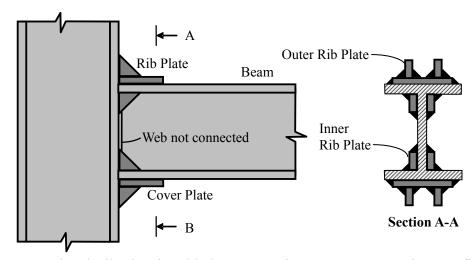


Figure 16. Cover Plated Rib Plated Welded Strong-Axis Moment Connection Configuration in Parallel Flange Sections: Cover Plates Transfer Part of Moment in the Form of Axial (Compressive and Tensile) Forces while (Outer) Rib Plates Transfer Axial and Shear Forces

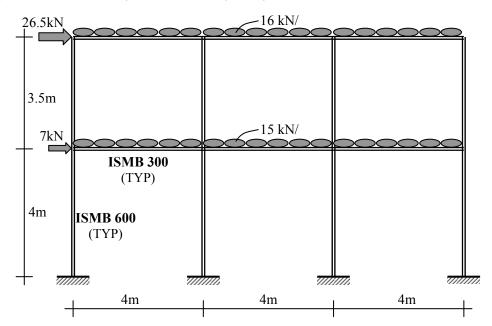


Figure 17. Sample Frame: Member Sizes, Boundary Conditions with Loadings

Tapered flange sections have small flange widths. Hence, in bolted connections, only a single line of weld is possible on either side of the web leading to long connection region. And, in welded connections, often, there is insufficient space between the two outer rib plates to weld them to the cover plates. In addition, due to tapering of these flanges, additional inner rib plates cannot be provided efficiently; these are crucial in minimizing stress concentration near the weld access holes. The following beam-to-column connection design example highlights the concerns in welded connections.

Figure 17 shows a simple 3-bay 2-storey frame made with Indian tapered-flange I-sections. The bay span considered is 4m. The uniformly distributed gravity load (including dead load, fraction of live load on roof and floor, and roof finish load) is 16 kN/m on the roof beam and 15 kN/m on the floor beam. The frame is considered to be in the most severe seismic zone and analysed for code specified load combinations. The maximum joint moment and shear forces for load combination 1.3(DL+LL+EL) are respectively 43 kNm and 48 kN. The beam-to-column connection is designed for this force.

In the common design practice, members and connections are designed based on the linear static analysis results. The web is considered to carry the shear and the two flanges carry the flexure, in the form of tension and compression. Accordingly, from the static analysis results above, 6 mm fillet welds of 100 mm length on both sides of the web are sufficient to carry the shear. The flanges can be connected to the column through a 10 mm full penetration butt weld, or by 10 mm fillet weld along the straight portions of the flanges. As there are no particular recommendations for the type of connection arrangement to be adopted in the existing Indian codes, such simple form of connection can be designed still adhering to the code provisions, if desired.

As an alternative, the beam-to-column connections can be designed using plastic theory wherein the connections can be designed for the nominal plastic moment that is to be transmitted from one member to another. Thus, under the condition of an extreme shaking, assuming that plastic hinges are formed at the beam ends, the design forces for connection design is the nominal plastic moment M_p (161.6 kNm) of the beam and a shear of 120.6 kN, considering the critical sections to lie at the beam-column interface. Thus, now the design shear and moment are increased by 1.5 to 2.8 times over the structural analysis results of the frame discussed earlier, and now, the connection designed earlier becomes inadequate. Further, the code does not specifically say that plastic analysis and design need to be done for seismic conditions. Thus, it remains at the hand of the designer to choose the type of analysis and design one wishes to do, and in the process, the structural safety is put at stake.

As the second alternative, now consider the overstrength based modification factors $R_y = 1.3$, $R_s = 1.24$ and $R_c = 1.0$. The design moment at the column face becomes 261 kNm plus the shear times the length of the connection reinforcement region and plastic hinge length. Thus, there is an increase of more than 62% in the design moment alone. This can cause premature failure of the connection even before the beam reaches its full plastic capacity resulting in collapse of the structure. Further, simple direct connections (directly welding the beam to the column) do not facilitate smooth flow of forces through the connection region; stress concentration at the beam flange-column flange junction severely affects the functioning of the connection. The cover-plated rib-plated connection with connection length of half the beam depth is an improvement (Figure 16). Using this, the associated shear force increases to 186.5 kN, an increase of about 55% compared to a value of 120.6 kN. However, this scheme works best on sections with wide non-tapered flanges. Tapered-flange Indian sections have very small flange width. As such, the available width of cover plate is much less and may be insufficient to transfer the forces in higher structures with higher forces. The example frame is a nominal two-storey lightly loaded structure chosen only with the

intention to discuss the important issues. Also, due to tapering of these flanges, additional inner rib plates cannot be provided efficiently to further reinforce the connection. These are important for minimizing stress concentrations at and near the weld access holes.

7. TAPERED FLANGE SECTIONS IN OTHER COUNTRIES

Tapered flange sections are still listed in different handbooks and codes across America and Europe (e.g., "Standard Beams" in American (AISC [21]) and Canadian [CISC [22]) handbooks, "Joists" in British Standard (BS 4-1 [23]). However, their use as main structural member in MRFs in seismic applications has become extinct. For instance, such sections are currently not available in the Canadian market, while their availability in the American and European market is questionable. Moreover, the maximum depth of the Standard Beams is 622 mm with flange width of only 204 mm, while that for the Joists, these are 254 mm and 203 mm, respectively. These are comparable to the Indian standard tapered-flange I-sections. For the already stated reasons, countries with advanced seismic provisions for design of steel structures use only wide-flange hot-rolled sections with uniform thickness flanges (e.g., the American W-shapes, British Universal Beams, and European wide flange HEA, HEB, & HEM sections).

On the other hand, in some Asian countries in high seismic regions, tapered-flange sections are still manufactured and are being used for structural applications. Possible reasons for this continued use of inappropriate sections include utilization of the old rolling mills without upgrading, lack of awareness towards seismic hazard of the region, and lack of code provisions.

8. SUMMARY

Tapered-flange I-sections, of at least a reasonable size, offer low section properties (namely moment of inertia, flange width, and nominal plastic moment capacity), violate stability requirements for stable post-yield behaviour particularly under strong seismic shaking, and offer constructional difficulties. Despite these deficiencies, tapered-flange I-sections are still being used extensively in many Asian countries. Thus, there is an urgent need to stop use of such sections, especially in seismic areas. This can be achieved by disseminating information regarding their deficiencies and challenges in their usage to the industry, architects and design engineers. Also, regional codes and specifications should restrict the use of such sections for seismic applications. Indirectly, this may even open up new opportunities for steel industry to manufacture larger seismically compact sections for the Asian market.

Table 1. Moment of Inertia and Nominal Plastic Moment Capacity of Indian Tapered-Flange I-Sections.

Section	Depth d	I_{xx}	M_p	-Flange 1-Sec Section	Depth d	I_{xx}	M_{p}
Name	(mm)	$(10^{-6} \mathrm{m}^4)$	(kNm)	Name	(mm)	(10^{-6} m^4)	(kNm)
ISLB 75	75	0.7	5.4		` ′		
ISLB 100	100	1.7	9.4	ISMB 100	100	2.6	14.5
ISLB 125	125	4.1	18.0	ISMB 125	125	4.5	20.3
ISLB 150	150	6.9	25.4	ISMB 150	150	7.3	27.3
ISLB 175	175	11.0	34.9	ISMB 175	175	12.7	41.2
ISLB 200	200	17.0	47.1	ISMB 200	200	22.4	62.6
ISLB 225	225	25.0	63.5	ISMB 225	225	34.4	86.0
ISLB 250	250	37.2	84.9	ISMB 250	250	51.3	114.9
ISLB 275	275	53.8	111.3				
ISLB 300	300	73.3	138.9	IGN (D. 200	300	86.0	161.6
ISLB 325	325	98.8	172.8	ISMB 300			
ISLB 350	350	131.6	212.2	ISMB 350	350	136.3	219.6
ISLB 400	400	193.1	273.5	ISMB 400	400	204.6	290.5
ISLB 450	450	375.4	348.1	ISMB 450	450	303.9	383.0
ISLB 500	500	385.8	440.3	ISMB 500	500	452.2	512.8
ISLB 550	550	531.6	553.7	ISMB 550	550	648.9	670.5
ISLB 600	600	758.7	696.6	ISMB 600	600	918.1	867.8
	150	8.4	31.5	ISHB 150	150	14.6	53.4
ISWB 150				ISHB 150	150	15.4	56.8
				ISHB 150	150	16.4	60.5
ISWB 175	175	15.1	48.4	_3	130	10.4	00.5
ISWB 200	200	26.3	73.0	ISHB 200	200	36.1	98.9
				ISHB 200	200	37.2	102.4
ISWB 225	225	39.2	96.9	ISHB 225	225	52.8	128.5
				ISHB 225	225	54.8	134.1
ISWB 250	250	59.4	131.8	ISHB 250	250	77.4	169.2
15 W D 250				ISHB 250	250	79.8	175.5
ISWB 300	300	98.2	182.3	ISHB 300	300	125.5	229.3
				ISHB 300	300	129.5	238.1
ISWB 350	350	155.2	247.9	ISHB 350	350	191.6	301.6
				ISHB 350	350	198.0	313.5
ISWB 400	400	234.3	328.0	ISHB 400	400	280.8	388.7
				ISHB 400	400	288.2	402.7
ISWB 450	450	350.6	435.8	ISHB 450	450	392.1	485.5
				ISHB 450	450	403.5	502.2
ISWB 500	500	522.9	585.1				
ISWB 550	550	749.1	760.8				
ISWB 600_1		1062.0	987.8				
ISWB 600_2	600	1156.3					

Table 2. Moment of Inertia and Nominal Plastic Moment Capacity of
Some Representative AISC I-Sections.

Section	Depth d	I_{xx}	M_{p}
Name	(mm)	$(10^{-6} \mathrm{m}^4)$	(kNm)
W 4 × 13	106	4.7	25.7
W 5 × 19	131	10.9	47.5
W 6 × 25	162	22.2	77.4
W 8 × 67	229	113.2	287.6
W 16 × 100	431	620.2	811.2
W 18 × 311	567	2897.0	3084.9
W 21 × 402	661	5078.0	4629.4
W 24 × 492	753	7950.0	6350.0
W 27 × 539	826	10613.9	7701.9
W 30 × 581	899	13735.6	9053.9
W 33 × 619	977	17398.5	10487.7
W 40 × 655	1108	23517.1	12536.1

LIST OF SYMBOLS

The following symbols are used in this paper:

C_{pr}	Factor to account for possible strain-hardening
$\dot{C_w}$	Warping constant
E	Modulus of elasticity
E_s	Modulus of elasticity of steel
F_u	Ultimate (tensile) strength
F_{y}	Minimum specified yield strength
$\dot{G_s}$	Shear modulus of steel
I	Moment of inertia
I_x , I_y	Moment of inertia about x and y axes
I_{xx}	Moment of inertia about strong axis of bending
J	Torsional constant
K	Effective column length factor
L	Length of column

M Bending moment M_p Nominal plastic moment capacity

 M_{pr} Maximum probable overstrength based moment

 M_y Yield moment P Axial load P_y Axial yield load

R Strength modification factor

 R_c Strength modification factor to account for compactness of section

 R_s Strength modification factor due to strain-hardening

 R_y Strength modification factor due to uncertainty in material yield strength Strength modification factor due to account for flexural-torsional buckling

 R_{λ} Strength modification factor due to account for flexural buckling in compression

- V Shear force
- V_p Section plastic shear capacity using minimum specified yield
- V_{pr} Connection design shear (equilibrium compatible shear corresponding to overstrength based moment at member ends)
- Y Limiting strength used in von Mises yield criterion
- Z Plastic section modulus
- b Width of plate element; width of flange of section
- d Depth of section
- *r* Radius of gyration
- *t* Thickness of plate element
- t_w Thickness of web
- Δ Deformation
- ε Strain
- ε_r Rupture strain
- ε_{sh} Strain at initiation of strain-hardening
- ε_{ν} Strain at maximum stress
- ε_v Yield strain
- λ Slenderness parameter
- λ_c Global slenderness parameter
- λ_p Limiting slenderness parameter for compact section
- λ_{ps} Limiting slenderness parameter for compact section with minimum guaranteed plastic rotation capacity
- λ_r Limiting slenderness parameter for non-compact section
- φ Curvature
- φ_{ν} Yield curvature
- μ Ductility
- μ_{sh} Curvature ductility at initiation of strain-hardening
- μ_u Ultimate curvature ductility
- μ_{ν} Curvature ductility at idealized yield
- μ_{ϕ} Curvature ductility
- θ_p Plastic rotation
- σ Stress
- σ_{xx} Normal stress
- τ_{xz} Shear stress
- τ_v Design shear stress

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